



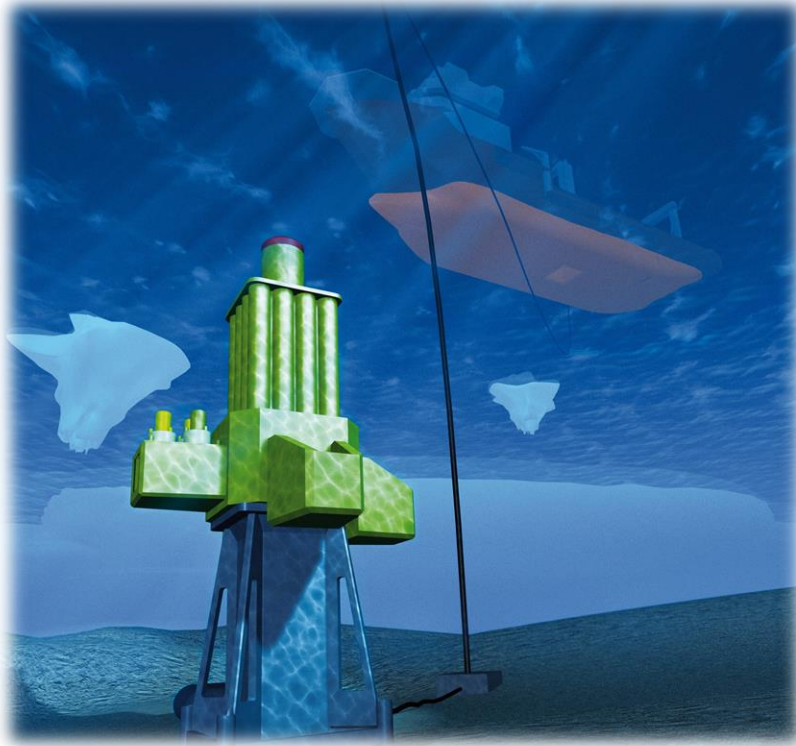
Robotizing the oil & gas drilling process

April 25 2018

Presented by:
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Software Manager



The dream





NABORS

- Founded 1966. Oil and natural gas.
- Houston Tx. 15 000 empl.
- World largest onshore fleet provider
- Main market are US and Middle-East
- Also provides offshore solutions
- Acquired Robotic Drilling Systems in 2017. Now **Canrig Robotics**.



Purpose

To responsibly help our customers meet the world's demand for oil and gas

Mission

We deliver best-in-class drilling performance through our exceptional people, execution, teamwork and technology

Vision

To be the driller of choice for employees, customers and investors

Values

Safety : Teamwork : Excellence : Accountability : Innovation



2018 rig market size

- 834 offshore drilling units today. ~53% utilization.
- 1110 land rigs in North-America. 972 elsewhere.
- All use 'traditional' drill floor technology with a high degree of manual operations

Semi-
submersible



Drillship

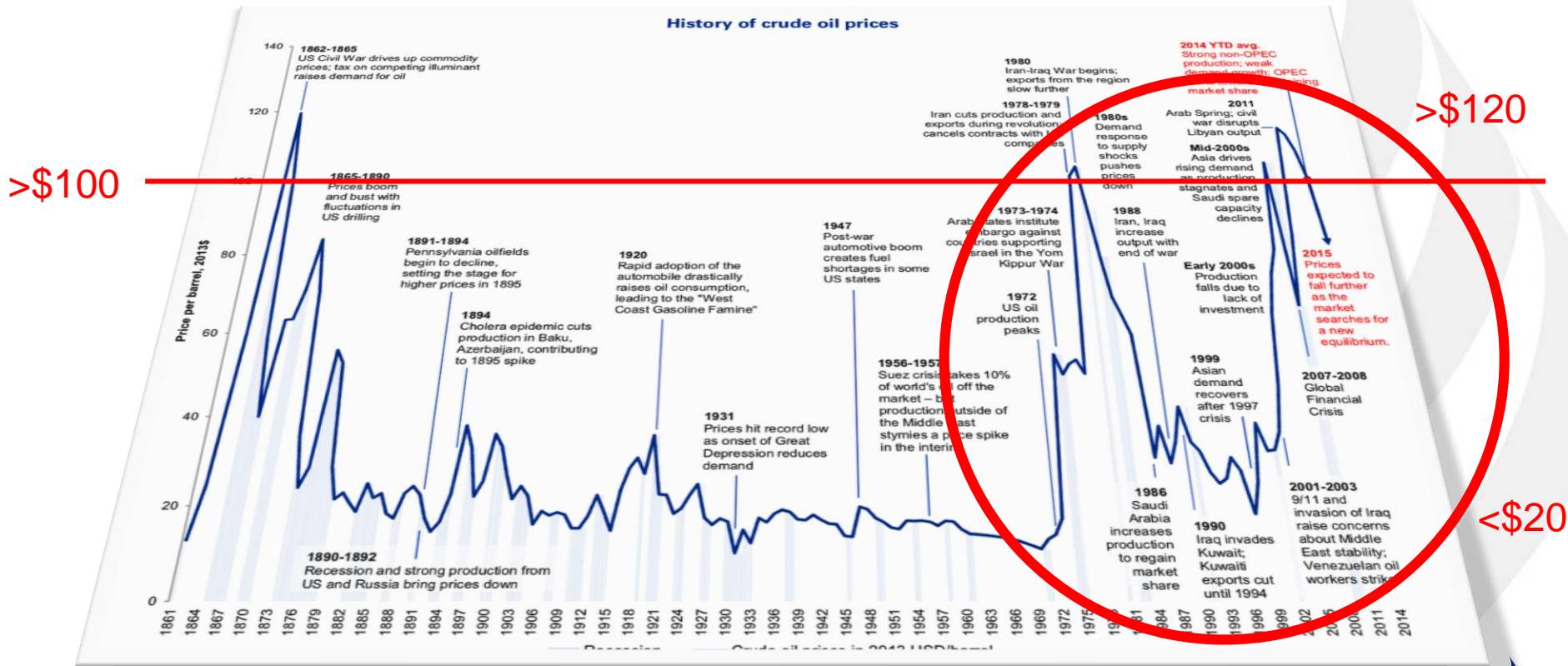


Jackup



Data from RigLogix and Baker Hughes Rig Count

Oil price cycle drives investment, crises drives innovation



Courtesy of Business Insider

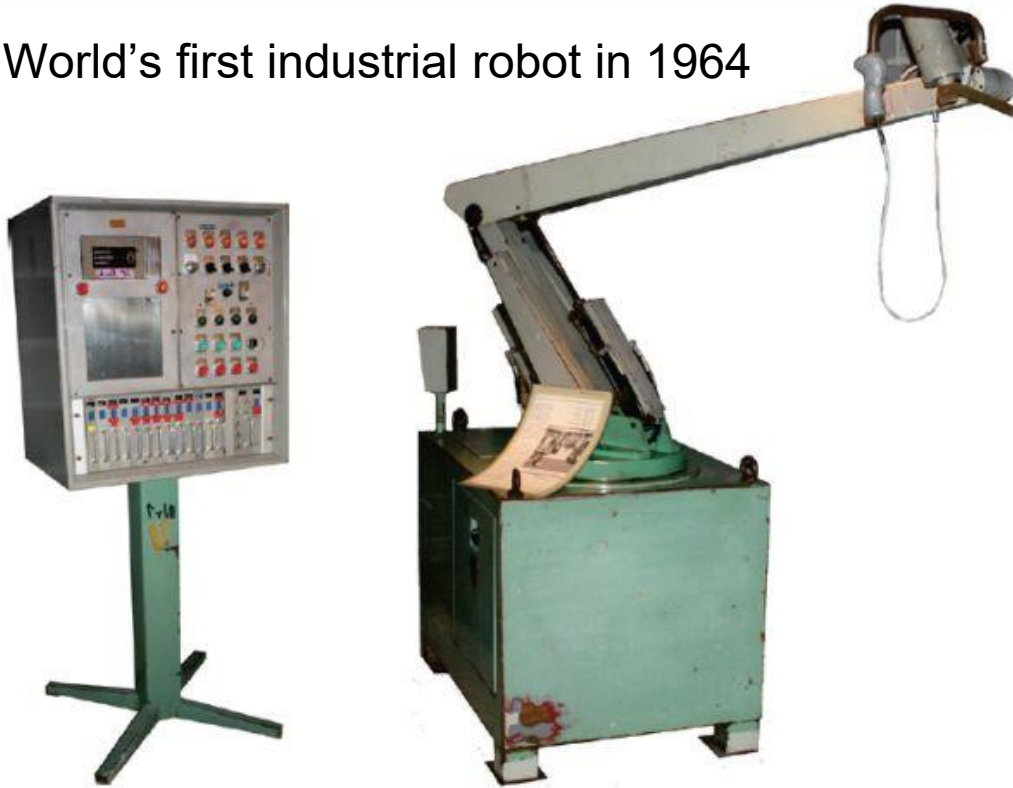
Problem formulation: minimize Non-Productive Time

- Drill fast, but not too fast!
- NPT = time not drilling
 1. Manual operations
 2. Tripping operation
- These are ideal to robotize and automate



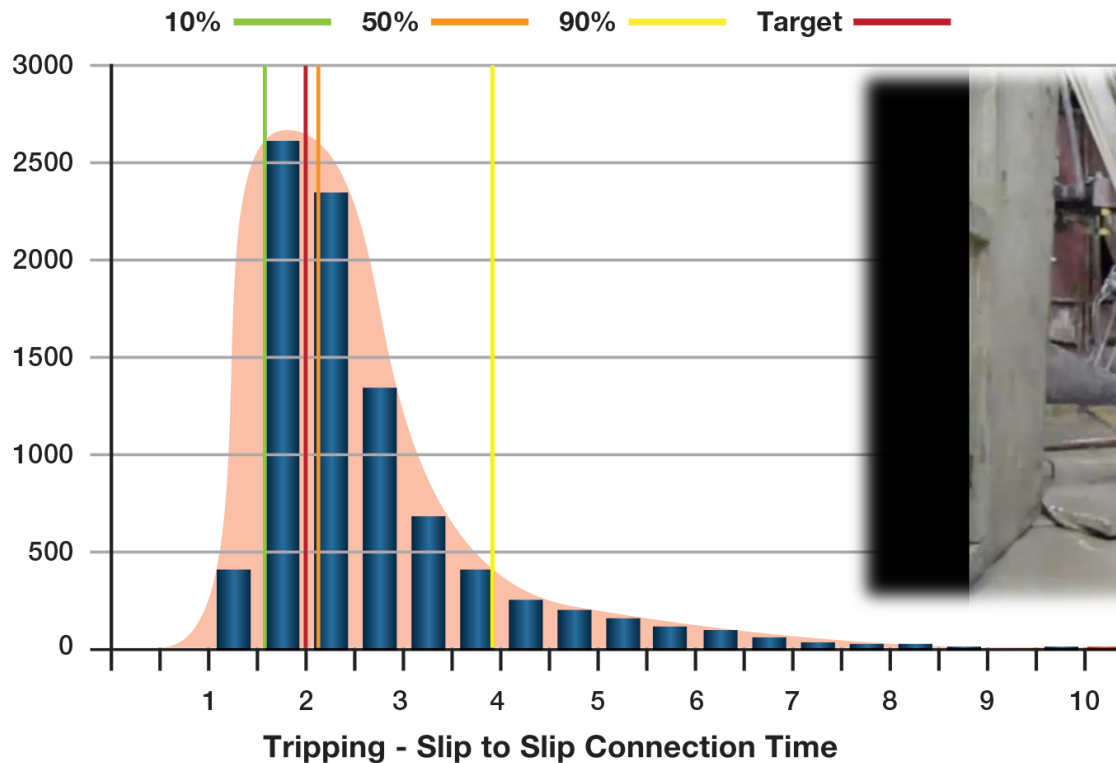
Automation in the car manufacturing industry

World's first industrial robot in 1964



Courtesy of ABB and BMW

Key Performance Indicator: Connection time



Land rig in 2018



3 men to connect a pipe

Courtesy of proNova-TDE

Derrick man's elevated office: Tripping in pipes



Derrick man's elevated office: Tripping in pipes



The view from 55' in the air



We really
need a
change..

This job is
mind-
numbing..



Manual operations

- Lifting subs
- Safety clamp
- Manual slips
- Stabbing guides
- Clamps for control lines
- Drill bit
- Mud bucket
- ...

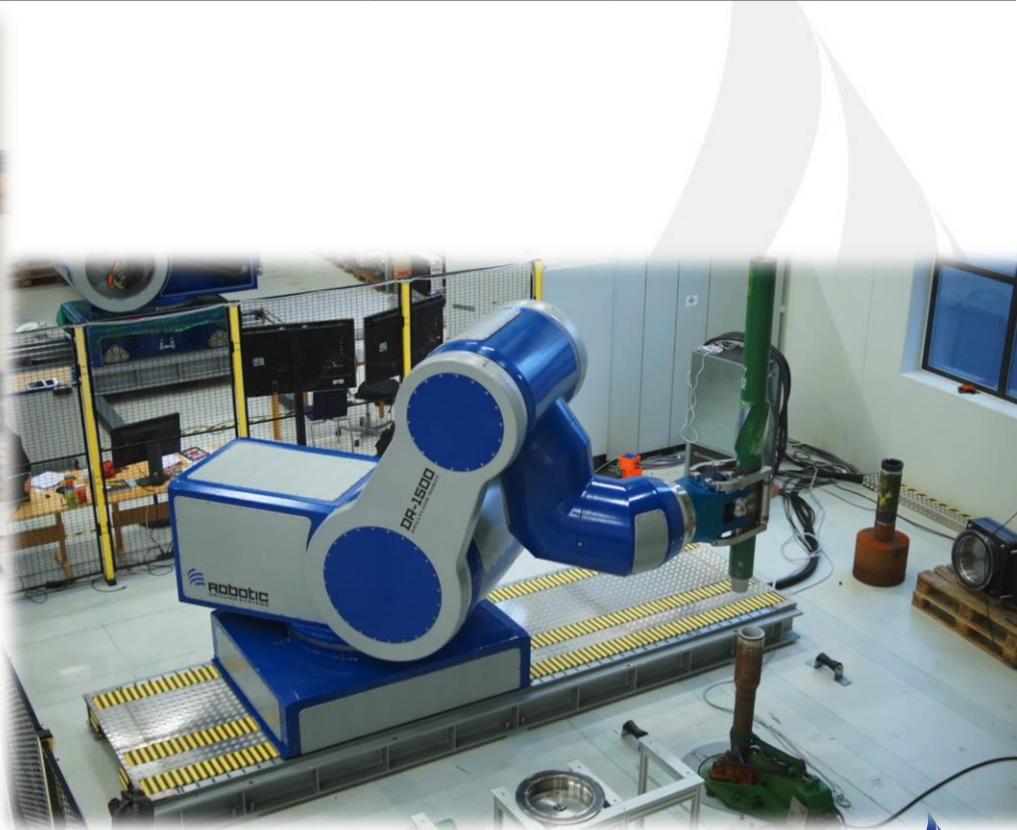


BHA MAKE-UP SEMI-SUBMERSIBLE

ROBOT VS. CONVENTIONAL



Multipurpose robot solves manual operations



First installation of Pipe Handler at US land rig

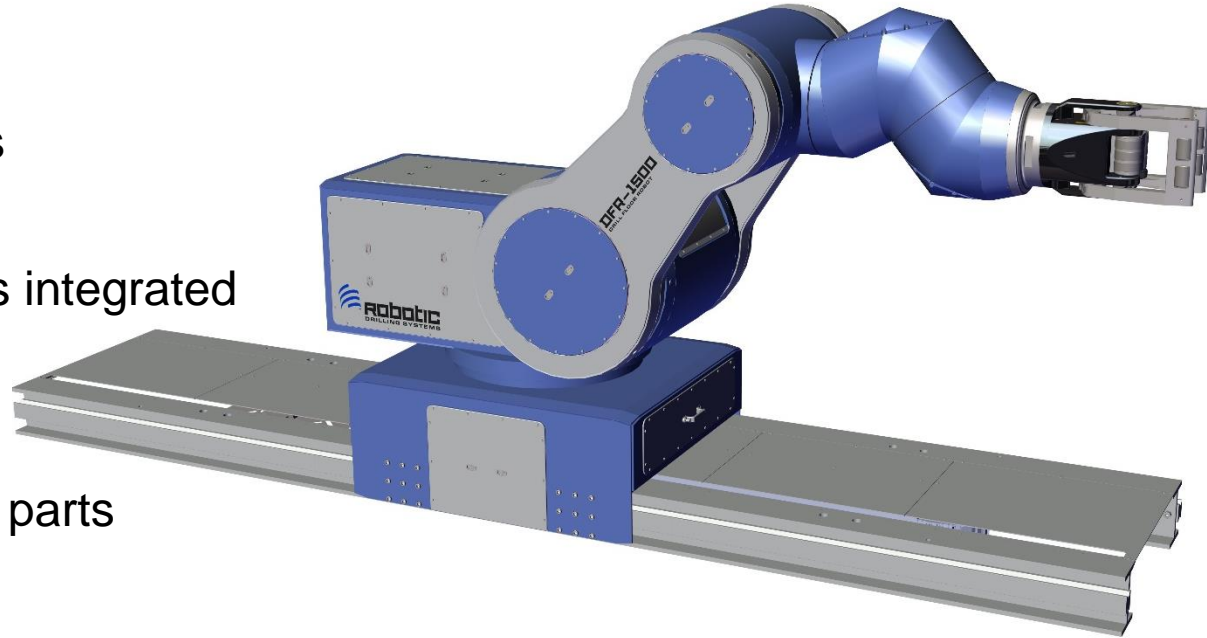




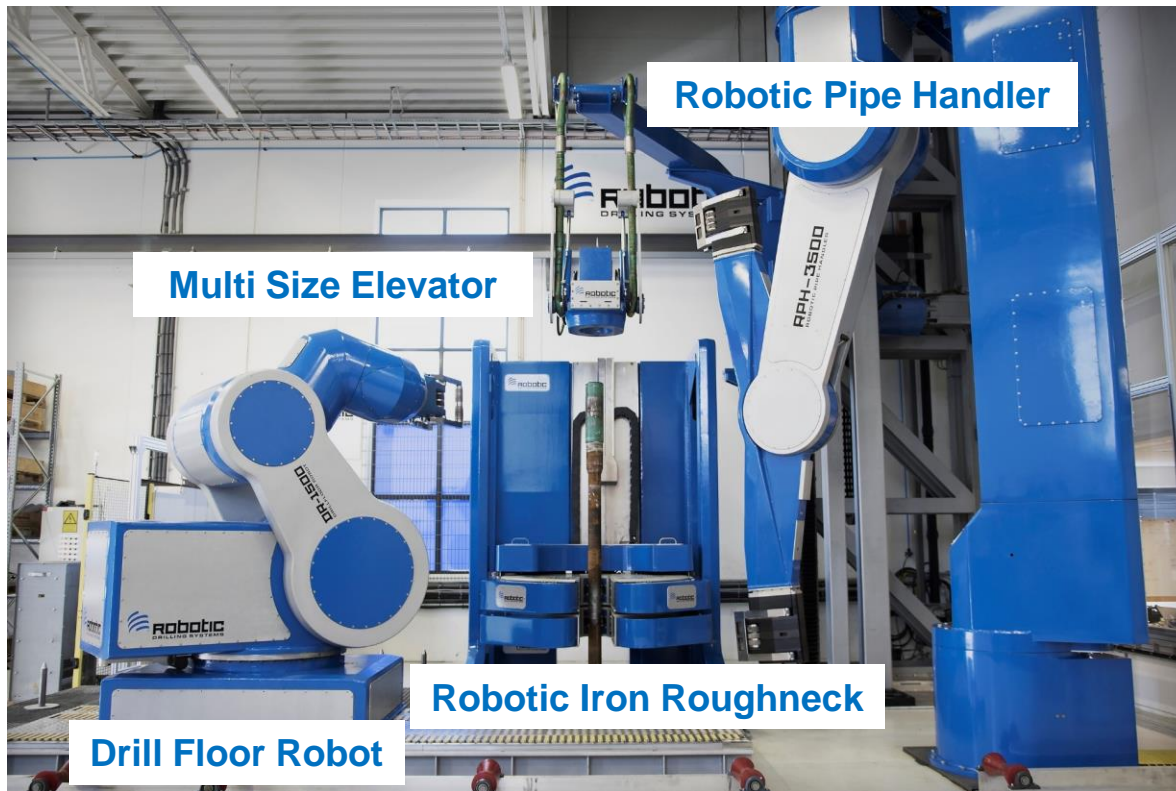
WHAT powers the robots?

Design Principles

1. Next generation products
2. Fully electric robots
3. All hardware components integrated
4. Maintenance free
5. Design life = 10 years
6. Standard equipment and parts
7. Focus on great design



Drill floor robots



High level control system topology

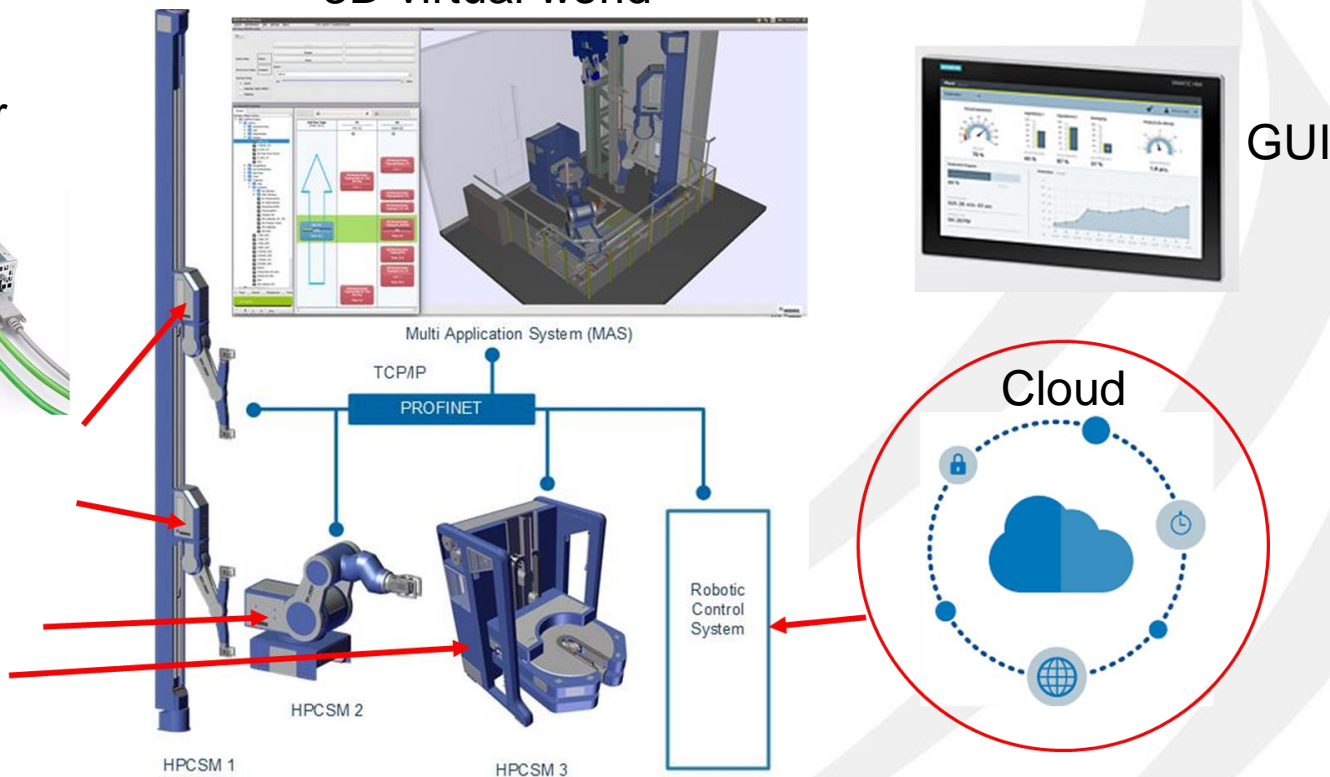


3D virtual world

Motion controller



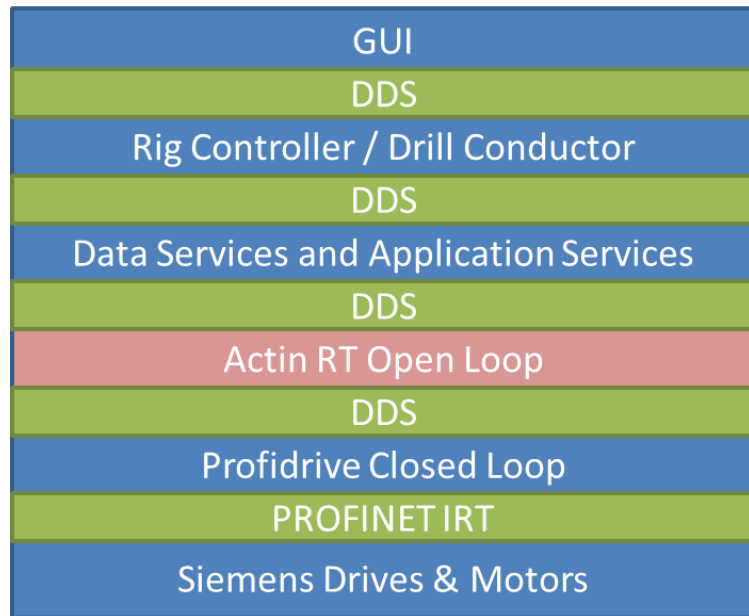
VFD
Motor
controller



DDS is the backbone of the robotic network



SIEMENS



DDS topics

- Robot motion
- Collision detection
- Object management
- Generic sensor data points
- Start/stop/pause a robot task



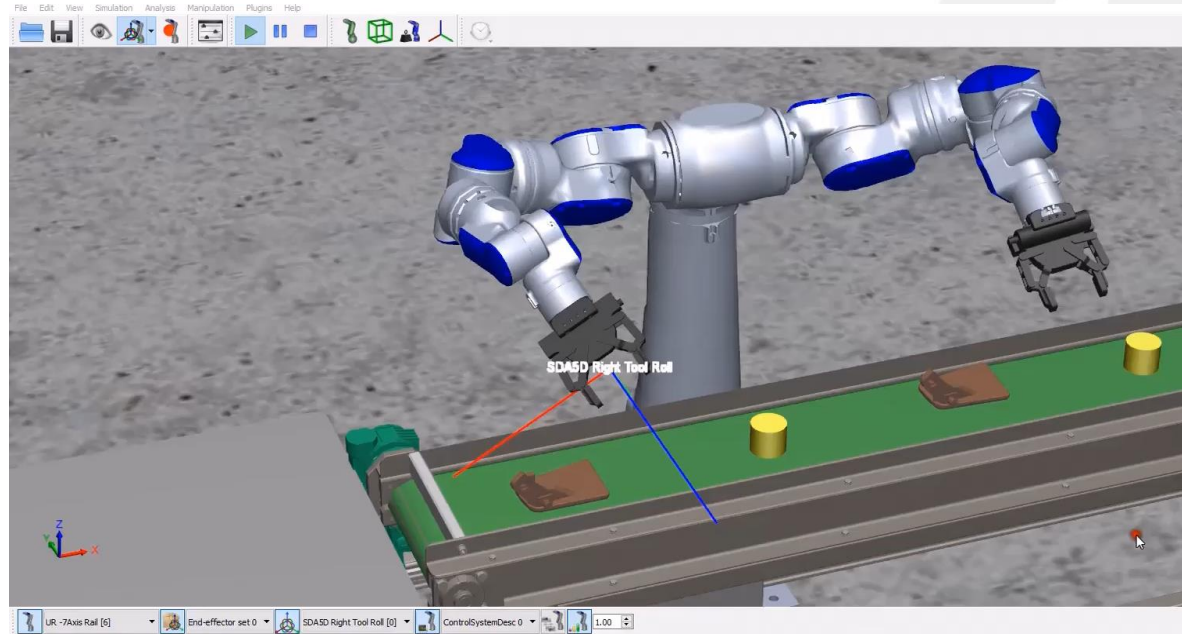
Powered by RTI DDS and Siemens Profinet real-time communication

Design phase

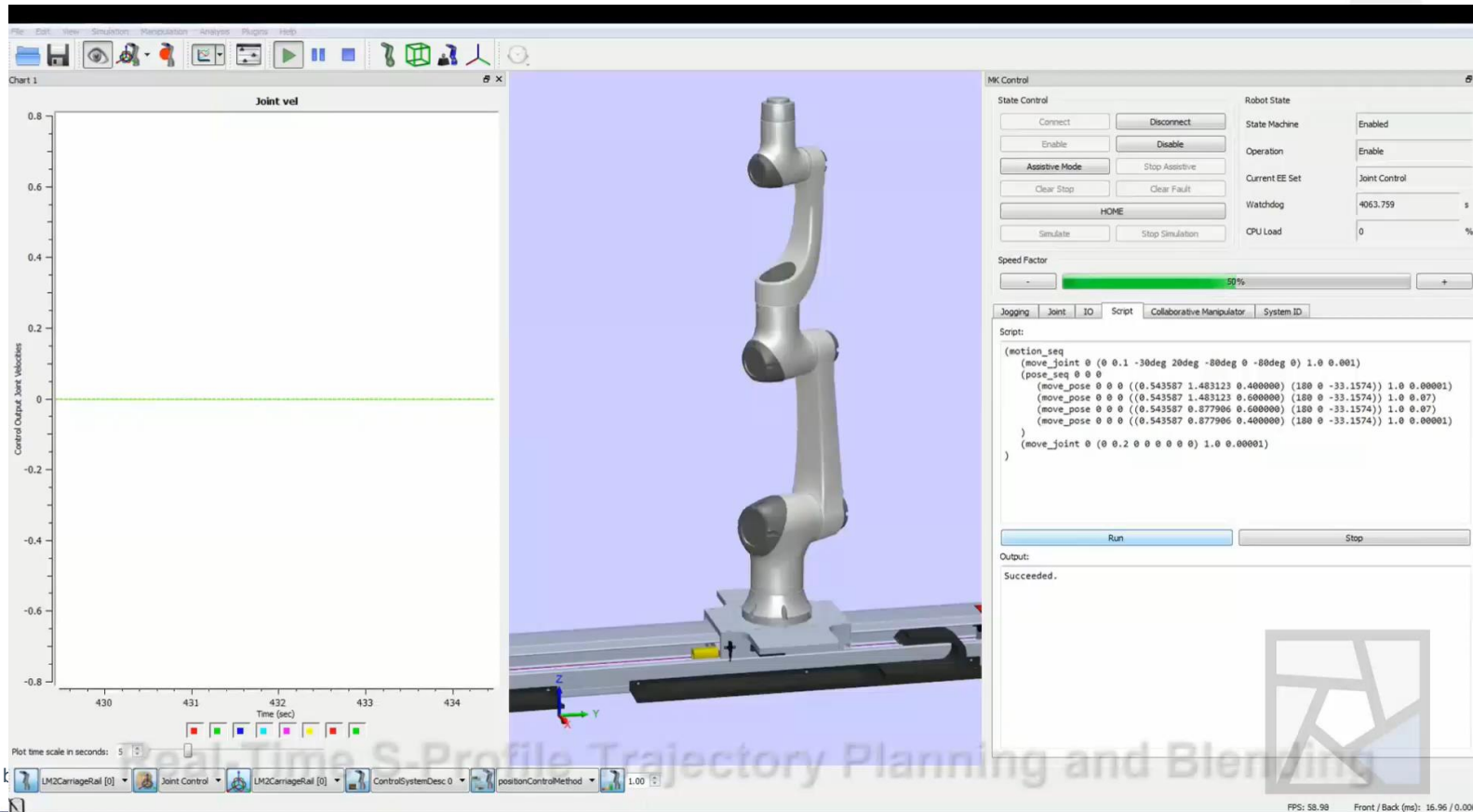
- Convert models from Solidworks
- Build a 3D world
- Simulate & Validate
- Simulation of
 - Kinematics
 - Dynamics
 - Program sequences



Powered by Actin®



Robot software ecosystem



Powered by

Real Time S-Profile Trajectory Planning and Blending



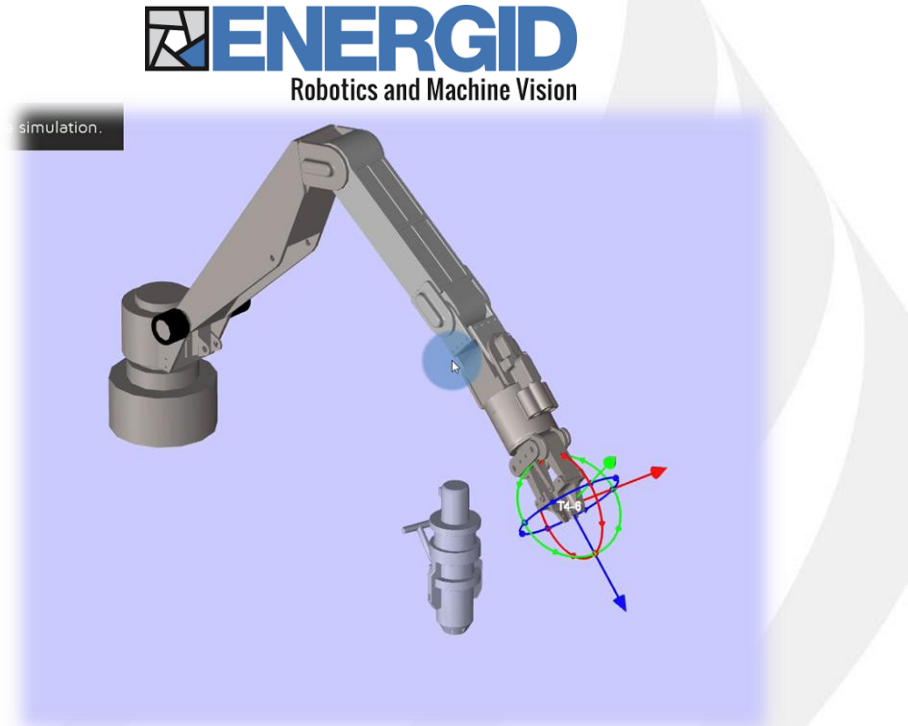
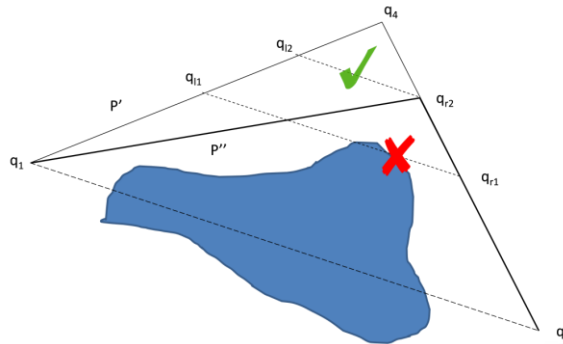
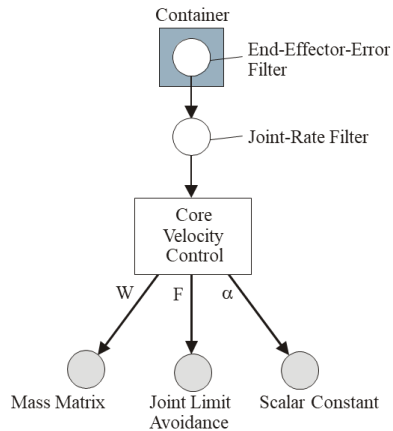
LM2CarriageRail [0] Joint Control LM2CarriageRail [0] ControlSystemDesc 0 positionControlMethod 1.00

FPS: 58.98 Front / Back (ms): 16.96 / 0.000



Robot real-time system

- On-the-fly path programming, A to B
- Real-Time collision avoidance
- Ahead of time 3D simulation
- Avoids joint limit, singularity and jerk
- High fidelity, high accuracy

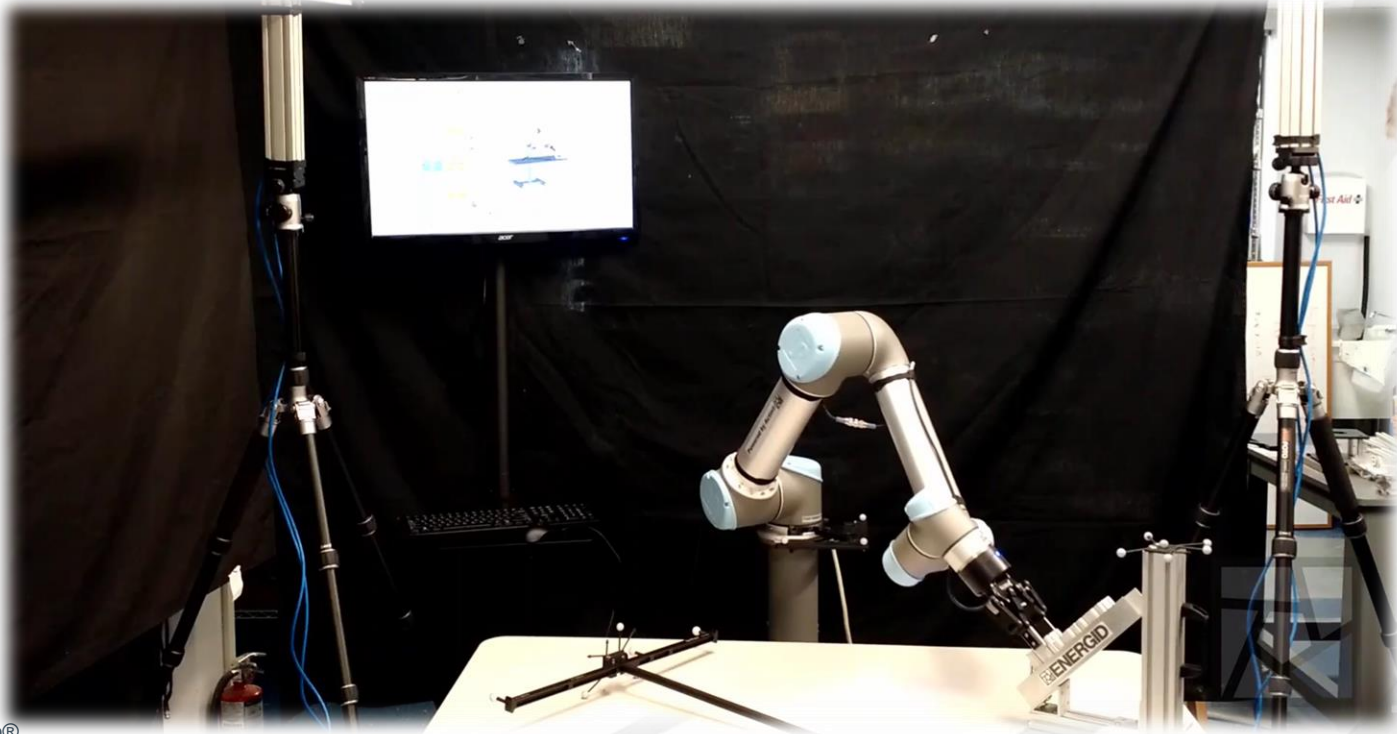


ENERGID
Robotics and Machine Vision

Dynamic control system

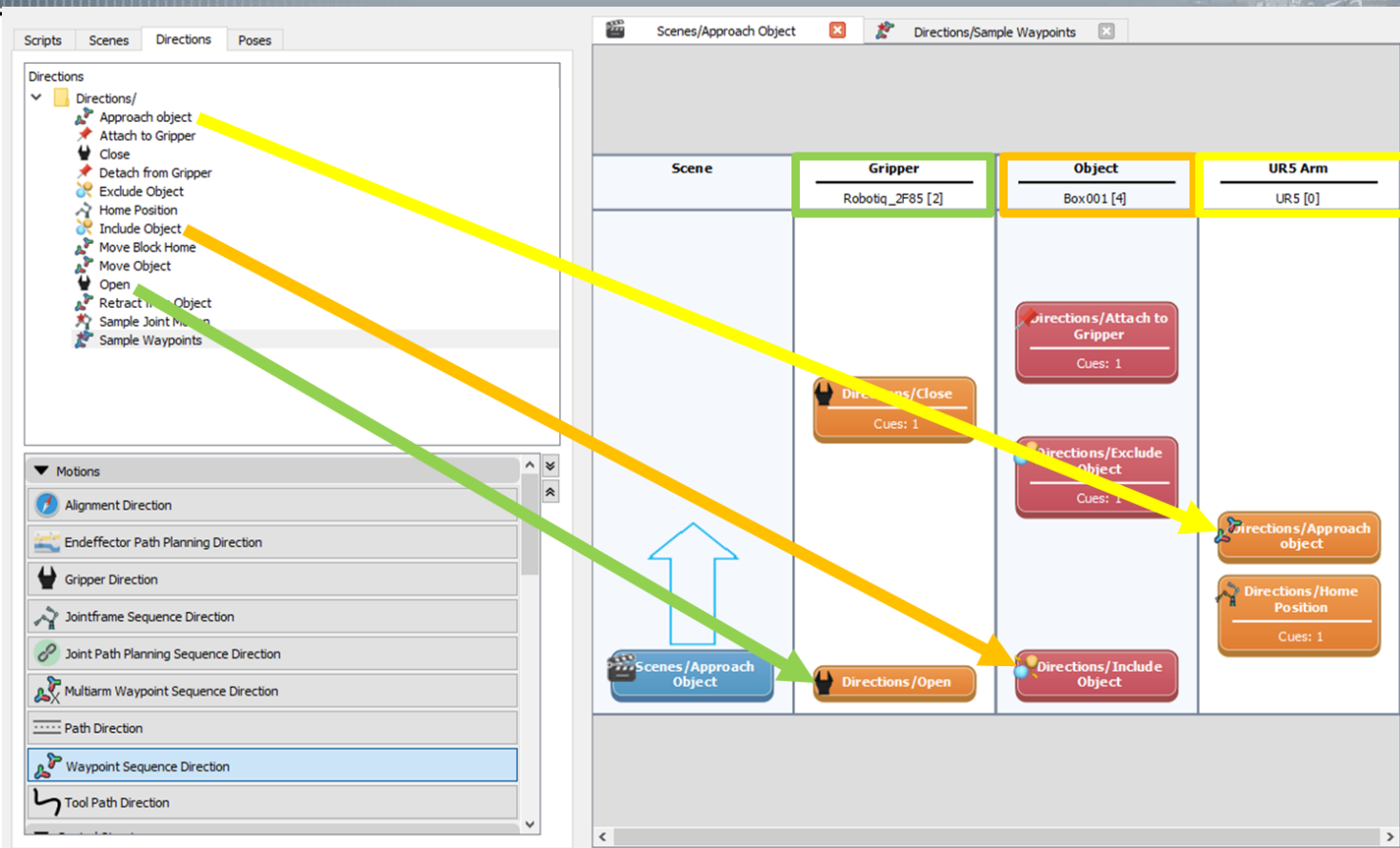


ENERGID
Robotics and Machine Vision



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Programming the robots





ROBOTIC
DRILLING SYSTEMS

- Manual operations still dominates the global rig fleet
 - = Robot will remove people from drill floor and save life and time.
- Tripping operation is the biggest time consumer
 - = Robotizing the tripping process will gain significant time and cost savings
- RTI Connex plays a vital part distributing real-time messages across the robot system



Thank you!

